neighbour distances in terms of the angle subtended at the centre of the sphere for the hard and soft cases. The hard data are a compilation from Clare & Kepert (1986), Kottwitz (1991), Lazic, Senk & Seskar (1987), Mackay, Finney & Gotoh (1977), Szekely (1974) and Tarnai & Gaspar (1983, 1991).

The case of N = 24 for m = 1 produces a distorted snub cube which has three near-neighbour distances. As *m* is increased the three separate values converge to a single value approaching 0.74420 for the true snub cube. Table 4 shows the convergence of the distances with increasing power of *m*.

I thank Professor Alan Mackay for helpful comments and suggestions and Dr Tibor Tarnai for showing so much interest and support. I am also deeply indebted to Dave Hatter of the Polytechnic of East London for teaching me the art of computer programming.

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Acta Cryst. (1992). A48, 69-70

**Improvement of the tangent formula by constraints based on additional information. II.** By JORDI RIUS and CARLES MIRAVITLLES, Institut de Ciencia de Materials (CSIC), Campus Universitari de Bellaterra, 08193 Cerdanyola, Barcelona, Spain

(Received 6 November 1990; accepted 15 July 1991)

#### Abstract

Recently, Rius & Miravitlles [*Acta Cryst.* (1991). A47, 567-571] have shown the viability of simultaneously refining the phases of the largest structure factors by least-squares minimization of the quantity  $R = \sum_{\mathbf{H}} w(\mathbf{H})[F(\mathbf{H})^2 - F_{calc}(\mathbf{H})^2]^2$  where the **H** summation extends over all measured reflections and  $w(\mathbf{H})$  is a weighting factor. Here, an alternative method of minimizing *R* by sequentially refining the phases  $\varphi_{\mathbf{h}}$  of the largest structure factors is suggested that takes advantage of the possibility of expressing  $\partial R/\partial \varphi_{\mathbf{h}} = 0$  as an explicit function of  $\varphi_{\mathbf{h}}$ .

Let the residual R be defined according to the expression  $R_{1}(\Phi) = \sum_{i} w(\mathbf{H})m(\mathbf{H})[E(\mathbf{H})^{2} - \mathbf{E}_{c}^{*}(\mathbf{H})\mathbf{E}_{c}(\mathbf{H})]^{2}, \quad (1)$ 

0108-7673/92/010069-02\$03.00

or, alternatively,

$$R_2(\Phi) = \sum_{\mathbf{H}} w(\mathbf{H}) m(\mathbf{H}) [E(\mathbf{H}) - E_c(\mathbf{H})]^2, \qquad (2)$$

where  $\Phi$  represents the collectivity of phases  $\varphi_h$  of the strong normalized structure factors E(H) and H denotes the measured reflections in one asymmetrical unit of the reciprocal space. The factor m(H) is the multiplicity of H and w(H) is the inverse of the variance associated with the difference  $E(H)^2 - E_c(H)^2$  [or  $E(H) - E_c(H)$ ]. Applying Sayre's equation (Sayre, 1952),  $E_c(H)$  may be approximated by

$$\mathbf{E}_{c}(\mathbf{H}) = E_{c}(\mathbf{H}) \exp i\varphi_{\mathbf{H}} = \theta(\mathbf{H}) \sum_{\mathbf{h}'} \mathbf{E}(\mathbf{h}') \mathbf{E}(\mathbf{H} - \mathbf{h}') \quad (3)$$

with  $\mathbf{E}(\mathbf{h}')$  and  $\mathbf{E}(\mathbf{H} - \mathbf{h}')$  belonging to the set of strong E's and  $\theta(\mathbf{H})$  a scaling factor. Obviously, the residual R will

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(4)

be a minimum for the correct  $\Phi$ . The condition for an (8), the following tangent formula results: extremum of  $R(\Phi)$  is

$$\partial R / \partial \varphi_{\mathbf{h}} = -2 \sum_{\mathbf{H}} m(\mathbf{H}) \ \Delta E(\mathbf{H}) \{ \mathbf{E}_{c}^{*}(\mathbf{H}) [\partial \mathbf{E}_{c}(\mathbf{H}) / \partial \varphi_{\mathbf{h}} ] + [\partial \mathbf{E}_{c}^{*}(\mathbf{H}) / \partial \varphi_{\mathbf{h}}] \mathbf{E}_{c}(\mathbf{H}) \} = 0$$

for every  $\varphi_{\mathbf{h}} \in \Phi$ , where  $\Delta E(\mathbf{H})$  is  $w(\mathbf{H})[E(\mathbf{H})^2 - E_c(\mathbf{H})^2]$ for  $R_1$  or  $w(\mathbf{H})[E(\mathbf{H}) - E_c(\mathbf{H})]/[2E_c(\mathbf{H})]$  for  $R_2$ . By working (4) out and assuming a non-centrosymmetric space group, one finds that

$$0 = -4 \sum_{H} m(H) \theta(H) \Delta E(H)$$

$$\times \sum_{s} (\partial/\partial \varphi_{h}) \{E_{c}(-H)E(hR_{s})E(H-hR_{s})$$

$$+ E_{c}(-H)E(-hR_{s})E(H+hR_{s})$$

$$+ E_{c}(H)E(hR_{s})E(-H-hR_{s})$$

$$+ E_{c}(H)E(-hR_{s})E(-H+hR_{s})\} \qquad (5)$$

$$= -4 \sum_{H} m(H) \theta(H) \Delta E(H)$$

$$\times \sum_{s} (\partial/\partial \varphi_{h}) \{E_{c}(-HR_{s}^{-1})E(h)E(HR_{s}^{-1}-h)$$

$$+ E_{c}(-HR_{s}^{-1})E(-h)E(HR_{s}^{-1}+h)$$

$$+ E_{c}(HR_{s}^{-1})E(h)E(-HR_{s}^{-1}-h)$$

$$+ E_{c}(HR_{s}^{-1})E(-h)E(-HR_{s}^{-1}-h)$$

$$+ E_{c}(HR_{s}^{-1})E(-h)E(-HR_{s}^{-1}-h)$$

$$+ E_{c}(HR_{s}^{-1})E(-h)E(-HR_{s}^{-1}+h)\} \qquad (6)$$

$$= -8 \sum_{H'} \theta(H') \Delta E(H')(\partial/\partial \varphi_{h}) \{|E(-h)E_{c}(H')E(h-H')|$$

$$\times \cos (\varphi_{-h} + \varphi_{H'} + \varphi_{h-H'})\} \qquad (7)$$

$$= -8E(h) \sum_{H'} \theta(H') \Delta E(H')|E_{c}(H')E(h-H')|$$

$$\times \{-\sin \varphi_{h} \cos (\varphi_{H'} + \varphi_{h-H'})\} \qquad (8)$$

where  $R_s$  is the matrix of the sth point-group symmetry operation and the summation over H' also includes the reflections related by Laue symmetry. By isolating  $\varphi_{\mathbf{h}}$  in

$$\varphi_{\mathbf{h}} = \text{phase of} \left\{ \sum_{\mathbf{H}'} \theta(\mathbf{H}') \ \Delta E(\mathbf{H}') \mathbf{E}_{\mathbf{c}}(\mathbf{H}') \mathbf{E}(\mathbf{h} - \mathbf{H}') \right\}.$$
 (9)

The correctness of (9) was tested on the same onedimensional model structure described by Sayre (1952) and Rius & Miravitlles (1991) by using F values instead of E's in  $R_1$ . The test calculations with these data showed that (9) was indeed able to refine phases, provided that it was only applied for  $|\partial R/\partial \varphi_h|$  values greater than a threshold limit value (TLV), *i.e.* for  $|\partial R/\partial \varphi_h| < TLV$ , the old value of  $\varphi_{h}$  was assumed to be its new estimate. The best TLV was empirically determined. If it was chosen too small, the phase-refinement process became unstable. On the contrary, if it was too large, the refinement did not converge.

Finally, combination of (9) with the conventional tangent formula of Karle & Hauptman (1956) leads to the improved tangent formula

$$\varphi_{\mathbf{h}} = \text{phase of} \left\{ \sum_{\mathbf{h}'} \mathbf{E}(\mathbf{h}') \mathbf{E}(\mathbf{h} - \mathbf{h}') + c \sum_{\mathbf{H}'} \theta(\mathbf{H}') \Delta E(\mathbf{H}') \mathbf{E}_{c}(\mathbf{H}') \mathbf{E}(\mathbf{h} - \mathbf{H}') \right\}, \quad (10)$$

where the  $\mathbf{h}'$  summation only involves the strongest E's, and the H' summation extends over all reflections. The practical application of (10) requires, however, the prior estimation of the scaling factors  $\theta(\mathbf{H}')$ , the weighting factors  $w(\mathbf{H}')$  and the value of c at the different stages of the phase-refinement process. Practical results will be published elsewhere.

The financial support of the CSIC and of the DGICYT (Project PB89-0036) is gratefully acknowledged.

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Acta Cryst. (1992). A48, 70-71

High-accuracy ab initio form factors for the hydride anion and isoelectronic species. By AJIT J. THAKKAR, Department of Chemistry, University of New Brunswick, Fredericton, New Brunswick E3B 6E2, Canada, and VEDENE H. SMITH JR, Department of Chemistry, Queen's University, Kingston, Ontario K7L3N6, Canada

(Received 23 January 1991; accepted 14 May 1991)

## Abstract

Form factors computed from extremely accurate wave functions are tabulated for  $H^-$ , He,  $Li^+$  and  $Be^{2+}$  together with fits to Gaussian expansions of the standard form.

Nearly exact ab initio form factors are available (Thakkar & Smith, 1978) for the hydride ion and other two-electron atoms. These were computed from extremely accurate wave functions (Thakkar & Smith, 1977) which allow for electron correlation by inclusion of many terms with an explicit

dependence on the interelectronic distance. Although the form factors listed in the crystallographic tables (Cromer & Waber, 1974) were computed from Hartree-Fock wave functions which neglect electron correlation completely, they have continued to be used in crystallographic studies. Perhaps this is because the electron-correlated form factors (Thakkar & Smith, 1978) were given in the form of Chebyshev expansions and not in tabular form.

Therefore, we present in Table 1 a listing of these highly accurate form factors for  $H^-$ , He, Li<sup>+</sup> and Be<sup>2+</sup> in the same format as in the crystallographic tables. The correlated form

0108-7673/92/010070-02\$03.00

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